

TITLE: BI-DIRECTIONAL FLATBED SCANNING
AND AUTOMATIC DOCUMENT FEED

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BACKGROUND OF THE INVENTION

10 Field of the Invention. The present invention relates generally to optical scanners and, more particularly to a method for bi-directional flatbed scanning and automatic document feed.

15 Background Art. Optical scanning and copying devices employ a method wherein data representative of a scanned object is produced by projecting an image of the scanned object onto an optical sensor. The optical scanning device may include scanner optics which may reduce the size of a projected image. The image of the scanned object is projected onto an optical sensor by linear increment by means of a moving scan line. The moving scan line is produced either by moving an image bearing media with respect to the scanner optical assembly or by moving the scanner optical assembly relative to an image bearing media. The optical sensor produce data representative of the intensity of the light projected thereon. These data may be digitized and stored on data storage media. Such stored data may be processed by a processing device to produce an image output or display.

25 Black and white or grayscale and some color optical scanning processes may require a single pass in order to acquire an image from which corresponding data is generated, processed and stored to produce an image of the object. Some color optical scanning processes require multiple passes in order to acquire multiple color component images from which corresponding data is generated and stored to produce a color image of the object. Typically data representative of red, green and blue component color images of the scanned object are produced and correlated for storage.

Various types of photosensor devices may be used in optical scanning

devices. One such photosensor device is the charge coupled photosensor device or "CCD". A CCD creates an electrical charge in response to exposure to light. The magnitude of the electrical charge created is dependent on the intensity and the duration of the light exposure.

5 In optical scanning devices CCD cells are aligned in linear arrays. Each cell has a portion of a scan line image projected thereon as the scan line sweeps across a scanned object. The charge in each of the cells is measured and discharged at a "sampling interval". The direction parallel to the scan line movement relative to the object is the "scan direction". A scanner linear
10 photosensor array includes a set of cells aligned in a "cross linear array", i.e. in a direction perpendicular to the scan direction. Each cell is defined by a width and a length, the width measured in the scan direction and the length measured in the cross linear direction. Scanners typically operate at a scanline sweep equal to one cell width per CCD sampling interval. At any time during a scanning
15 operation, each cell in the CCD array includes an area that corresponds to an area of the object which is being imaged. This area of the CCD array is referred to herein as a "cross linear sampling". The corresponding area of the scanned object is referred to herein as an "object linear segment".

In flatbed optical scanning devices and copiers of the prior art, image
20 bearing media is placed on a transparent platen and the carriage assembly scans the image from the top of the page to the bottom of the page while the image remains stationary on the transparent platen. When the top to bottom scan is complete, the carriage assembly returns to a top of the page position ready for the next top to bottom scan. In a black and white or one pass color scanning
25 device, two traverses of the page length are required to scan a single image. In a multiple or three pass color scanning device, six traverses of the page length are required to scan a single image.

In a flatbed optical scanning device including an automatic document feed (ADF), image bearing media will be fed in repeated sequence for positioning on
30 the flatbed for scanning and then on to an output document tray or document receiver. The carriage assembly repeatedly cycles from top to bottom and

bottom to top scanning media in repeated sequence from the top of the page to the bottom of the page until such time as the ADF no longer contains media for feeding. The process repeats until the last image is scanned and then the carriage assembly returns to a top of the page position ready for the next scan
5 job.

Processor operable image processing software processes digital data representative of the scanned image or images for storage, transmission, display, printing or other output.

10 It may be desirable to reduce the number of scanner carriage movement sequences by substantially 50 percent. It may be desirable to reduce scanning time by substantially 50 percent. It may also be desirable to increase the reliability of a scanning device by reducing total operation time for any given multi-page scanning task. It may also be desirable to improve long term scan and print quality by reducing the total mechanical stress over the life of the
15 scanning device caused by vibration by reducing total operation time.

SUMMARY

20 The present invention is directed to a method for scanning an object including the steps of moving a first scanline relative to the object in a top to bottom scan direction, i.e. from the top of an image bearing media to the bottom of the image bearing media, followed by moving a second scanline relative to the object in a bottom to top scan direction, i.e. from the bottom of an image bearing media to the top of the image bearing media. An optical scanning device for
25 producing machine-readable data representative of an object includes a transport assembly for moving a scanline relative to the object in a top to bottom scan direction from the top of the object to the bottom of the object. The transport assembly is also configured for moving the scanline relative to the object in a bottom to top scan direction from the bottom of the object to the top of the object.
30 The optical scanning device also includes an imaging assembly operable in successive sampling intervals for generating a plurality of cross linear samplings

image data representative of the object and a processing device responsive to a signal indicating a scan direction for selectively indexing a plurality of cross linear samplings in either a forward sequential order or a reverse sequential order.

In one preferred embodiment of the invention, the method for scanning an image includes the steps of feeding a first image bearing media through an automatic document feeding device to a flatbed scanner. The media is positioned on a transparent platen and the media is scanned from the top of the media to the bottom of the media. Once the carriage assembly reaches a top to bottom scan direction limit, the first image bearing media is transported off the platen and a second image bearing media is positioned on the transparent platen. The second media is scanned from the bottom to the top of the media, i.e. in a bottom to top scan direction. This sequence may be repeated until such time as the ADF no longer contains media to feed, or until such time as a stop scan command is provided by the scanning device controller.

Processor operable image data processing software indexes data representative of successive cross linear sampling.

For those images scanned from the top to the bottom of the media, typically even odd numbered images, or odd numbered scanning passes, each successive "cross linear sampling" is forward indexed in sequential order, i.e. $S_1, S_2, S_3, \dots, S_X$, where S is a cross linear sampling from 1 through X . When compiled, the image data order replicates the object.

For those images scanned from the bottom of the media to the top of the media, typically even numbered images, or even numbered scanning passes, each successive "cross linear sampling" is reverse indexed in reverse sequential order, i.e. $S_X, S_{X-1}, S_{X-2}, S_{X-3}, \dots, S_1$, where S is a cross linear sampling from X through 1. Once again, when compiled, the image data order replicates the object.

The invention substantially reduces the number of scanner carriage movements and the scanning time. Since the scanner carriage movement is reduced, the reliability of the system is improved because of less wear and tear. It also reduces the vibration impact on the printing system because of reduced

carriage movement which improves print quality.

DESCRIPTION OF THE DRAWINGS

5 Figure 1 is a representative perspective view of a flatbed scanning device including an automatic document feeder;

 Figure 2 is a representative perspective view of a flatbed scanning device including an automatic document feeder;

 Figure 3 is a representative perspective view of a flatbed scanning device
10 including an automatic document feeder;

 Figure 4 is a side cutaway view of a flatbed scanning device including an automatic document feeder;

 Figure 5 is a side cutaway view of a flatbed scanning device including an automatic document feeder;

15 Figure 6 is schematic diagram of a first scanned image section including a plurality of cross linear sampling $S_1, S_2, S_3, \dots, S_x$ compiled in a forward sequential indexing mode, the first scanned image section corresponding to a first object section;

 Figure 7 is schematic diagram of a second scanned image section
20 including a plurality of cross linear sampling $S_1, S_2, S_3, \dots, S_x$ compiled in a reverse sequential indexing mode, the second scanned image section corresponding to a second object section;

 Figure 9 is a block diagram illustrating a scanning device according to the present invention; and

25 Figure 9 is a flow chart depicting the steps of a method for bi-directional flatbed scanning and automatic document feed.

DESCRIPTION

30 Figures 1 through 5 show optical scanning device 10 including automatic document feeder 11 which is adapted for producing machine readable data

representative of a scanned object. In Figure 1, automatic document feeder 11 is shown having image bearing media 13 positioned thereon for processing. As shown in Figures 2 through 5, optical scanning device 10 includes illumination assembly 17 which is supported and transported by carriage assembly 28 below transparent platen 14 (shown in Figures 3 through 5). Illumination assembly 17 reciprocatingly traverses below transparent platen 14 by operation of transport assembly 25 which includes motor 26, belt 27 and carriage assembly 28. Imaging assembly 20 is supported and transported by carriage assembly 28.

As seen in Figure 4 and 5, optical scanning device 10 includes automatic document feeder 11 including paper tray 12 and rollers 15A and 15B which drive belt 16 for transporting image bearing media 13. Paper tray 12 supports image bearing media 13 to be transported across transparent platen 14. Optical scanning device 10 also includes receiver 19 for containing media following scanning. Carriage assembly 28 reciprocatingly traverses below transparent platen 14. Imaging assembly 20 is supported and transported by carriage assembly 28. Carriage assembly 28 includes illumination assembly 17 and body 29 defining aperture 30 through which light is reflected. Imaging assembly 20 includes mirrors 31, 32, 33 providing folded light path P. Folded light path P extends through aperture 30, to mirror 31, to mirror 32, to mirror 33, through optics 21 to photosensor 22. Photosensor 22 generates image data representative of image bearing media 13. Photosensor 22 may include grayscale or color data image capability.

As seen in Figure 4, first image bearing media 13A is fed across transparent platen 14 by automatic document feeder 11 and carriage assembly 28 traverses beneath transparent platen 14 in top to bottom scan direction 34 scanning media 13A. When controller 42 (shown in Figure 8), senses that carriage assembly 28 has initiated travel in top to bottom scan direction 34, imaging assembly 20 initiates the scan and sample cycle. Light is reflected by illuminated first image bearing media 13A through aperture 30 at mirrors 31, 32, 33 providing folded light path P extending through optics 21 to photosensor 22. Data representative of the intensity of light which is reflected by illuminated image

bearing media 13A is generated by photosensor 22.

Figure 6 is a schematic representation of first image bearing media 13A including object scan line 50A corresponding with cross linear sampling 51A. Image data 52 includes a plurality of cross linear samplings indexed in forward sequential order, i.e. $S_1, S_2, S_3, \dots S_X$. A scanner displacement of one scan line width, is represented by each cross linear sampling $S_1, S_2, S_3, \dots S_X$. First image bearing media 13A is illuminated by illumination assembly 17. Light is reflected by illuminated first image bearing media 13A creating folded light path P extending through aperture 30, to mirror 31, to mirror 32, to mirror 33, through optics 21 of imaging assembly 20 to photosensor 22. Image data 52 representative of the intensity of light which is reflected by illuminated first image bearing media 13A is generated by photosensor 22. As shown in Figure 6, processor 40 indexes image data 52 from photosensor 22 from successive cross linear samplings in forward sequential order, i.e., $S_1, S_2, S_3, \dots S_X$.

Referring to Figure 5, once carriage assembly 28 reaches top to bottom scan direction travel limit 36, first image bearing media 13A is transported off transparent platen 14 to receiver 19, second image bearing media 13B is positioned on transparent platen 14 by operation of automatic document feeder 11 and carriage assembly 28 reverses travel direction to bottom to top scan direction 35. Controller 42 (shown in Figure 8), senses that carriage assembly 28 has initiated travel in bottom to top scan direction 35. Imaging assembly 20 initiates the scan and sample cycle. Light is reflected by illuminated second image bearing media 13B through aperture 30 at mirrors 31, 32, 33 providing folded light path P extending through optics 21 to photosensor 22. Data representative of the intensity of light which is reflected by illuminated second image bearing media 13B is generated by photosensor 22.

Figure 7 is a schematic representation of second image bearing media 13B including object scan line 50B corresponding with cross linear sampling 51B. Image data 53 includes a plurality of cross linear samplings indexed in reverse sequential order, i.e. $S_X, S_{X-1}, S_{X-2}, S_{X-3}, \dots S_1$. A scanner displacement of one scan line width, is represented by each cross linear sampling $S_X, S_{X-1}, S_{X-2}, S_{X-3}, \dots$

5 . S₁. Second image bearing media 13B is illuminated by illumination assembly 17. Light is reflected by illuminated first image bearing media 13B through aperture 30 at mirrors 31, 32, 33 providing folded light path P extending through optics 21 to photosensor 22. Image data 53 representative of the intensity of light which is reflected by illuminated first image bearing media 13B is generated by photosensor 22. As shown in Figure 7, processor 40 indexes image data 53 from photosensor 22 from successive cross linear samplings in reverse sequential order, i.e., S_x, S_{x-1}, S_{x-2}, S_{x-3}, . . . S₁.

10 Once carriage assembly 28 reaches bottom to top scan direction limit 37, second image bearing media 13B is transported off transparent platen 14 to receiver 19, a third image bearing media (not shown) is positioned on transparent platen 14 by operation of automatic document feeder 11 and the previously described sequence may be repeated until such time as controller 42 (shown in Figure 8), senses that paper tray 12 no longer contains image bearing media 13
15 to be fed by automatic document feeder 11, or until such time as a stop scan command is provided by controller 42.

As shown in Figure 8, optical scanning device 10 may also include or may be connected to a data processor 40, for example a personal computer, for processing data from photosensor 22. One arrangement includes scanning
20 device 10 including controller 42 and a scan direction sensor 41 connected to data processor 40. Data processor 40 is connected to data storage 43, display device 44 and printer 45.

Figure 9 is a flow chart depicting the steps of a method for bi-directional flatbed scanning and automatic document feed. The process is initiated at
25 START 55. Media is fed by an automatic document feeder at FEED MEDIA 56 and a scanning operation initiates at INITIATE SCAN 57. The controller senses the direction of carriage assembly movement at SENSE CARRIAGE DIRECTION 58. A top to bottom scan direction is sensed at TOP TO BOTTOM SCAN DIRECTION 59 and scan/sampling process begins at BEGIN SAMPLING 60.
30 Each successive cross linear sampling is forward indexed at FORWARD INDEX CROSS LINEAR SAMPLINGS 61. When device controller senses a top to

bottom scan direction limit at SENSE CARRIAGE TRAVEL LIMIT 62, the controller queries the ADF to sense the presence of additional media for scanning at MEDIA PRESENT? 63. If media is present as indicated at YES 64, the process returns to FEED MEDIA at 56.

5 Scanning operations initiate once again at INITIATE SCAN 57. The controller senses the direction of carriage assembly movement at SENSE CARRIAGE DIRECTION 58, and a bottom to top scan direction is sensed at BOTTOM TO TOP SCAN DIRECTION 65. The scan/sampling process begins at BEGIN SAMPLING 66 and each successive cross linear sampling is reverse
10 indexed at REVERSE INDEX CROSS LINEAR SAMPLINGS 67. When device controller senses the travel limit at SENSE CARRIAGE TRAVEL LIMIT 62, the controller queries the ADF to sense the presence of additional media for scanning at MEDIA PRESENT? 63. If media is not present, as indicated at NO 68, the process ends the scan operation at END SCAN 69.

15 While this invention has been described with reference to the detailed embodiments, this is not meant to be construed in a limiting sense. Various modifications to the described embodiments, as well as additional embodiments of the invention, will be apparent to persons skilled in the art upon reference to this description. It is therefore contemplated that the appended claims will cover
20 any such modifications or embodiments as fall within the true scope of the invention.